

## AFTER UPDATE INSTALLATION

1. Connect the Pinpoint Gateway Module, (Arrow facing arrow > <)
2. Provide Power to the Xi Trolling Motor and deploy the motor.
3. Once GPS is acquired, Power-On the MFD (Lowrance/Simrad).
4. Go To: Pages>Settings>Network>Select Auto Configure
5. Perform a compass calibration (M111) **two times**. *Refer to the appropriate operations manual for the procedure.*
6. Disconnect power from the motor.
7. Connect power to the motor.
8. Wait for the motor to signal the pinpoint ready tone.
9. Perform a keel alignment calibration (M112). *Refer to the appropriate operations manual for the procedure.*
10. First time operation of Cruise Control function should be performed via the Remote. *Refer to the appropriate operations manual for the procedure.*
11. The motor is ready for normal operation.